

SERIES DIODE CONFIGURATIONS

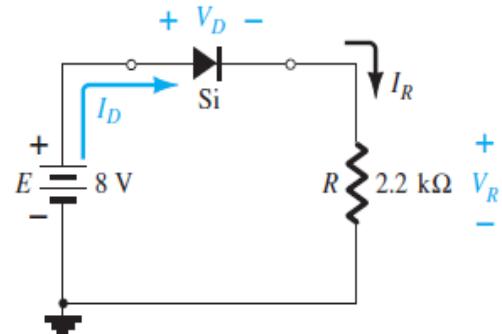
EXAMPLE 1:

For the series diode configuration of Figure determine V_D , V_R , and I_D .

$$V_D = 0.7 \text{ V}$$

$$V_R = E - V_D = 8 \text{ V} - 0.7 \text{ V} = 7.3 \text{ V}$$

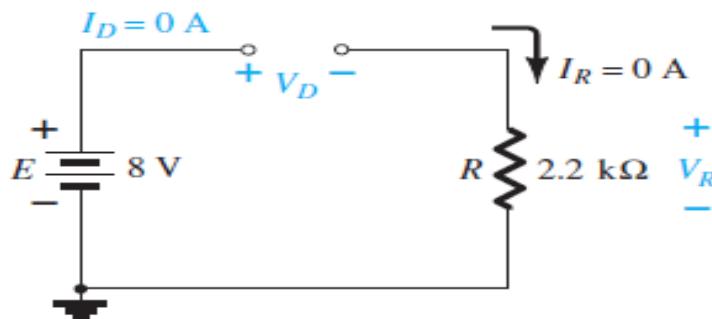
$$I_D = I_R = \frac{V_R}{R} = \frac{7.3 \text{ V}}{2.2 \text{ k}\Omega} \cong 3.32 \text{ mA}$$



Repeat the Example with the diode reversed.

$$E - V_D - V_R = 0$$

$$V_D = E - V_R = E - 0 = E = 8 \text{ V}$$



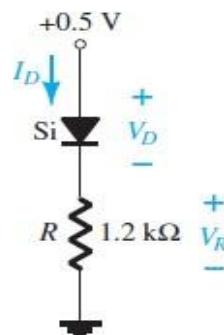
EXAMPLE 2:

For the series diode configuration of Figure, determine V_D , V_R , and I_D .

$$I_D = 0 \text{ A}$$

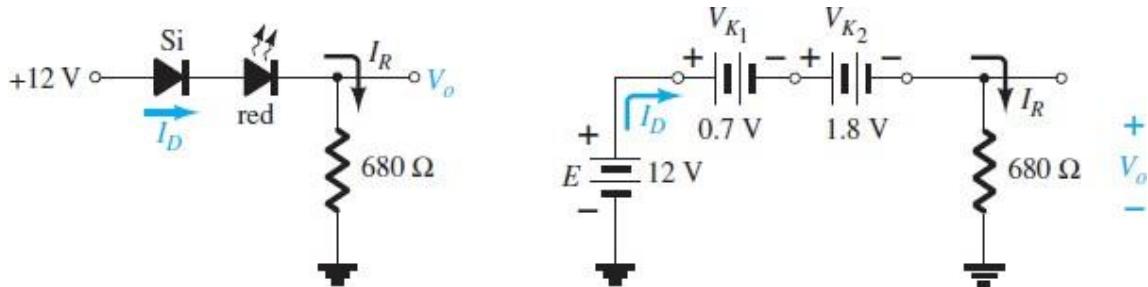
$$V_R = I_R R = I_D R = (0 \text{ A}) 1.2 \text{ k}\Omega = 0 \text{ V}$$

$$V_D = E = 0.5 \text{ V}$$



EXAMPLE 3:

Determine V_o and I_D for the series circuit of the figure.



$$V_o = E - V_{K_1} - V_{K_2} = 12 \text{ V} - 2.5 \text{ V} = 9.5 \text{ V}$$

$$I_D = I_R = \frac{V_R}{R} = \frac{V_o}{R} = \frac{9.5 \text{ V}}{680 \Omega} = 13.97 \text{ mA}$$

EXAMPLE 4:

Determine I_D , V_{D2} , and V_o for the circuit

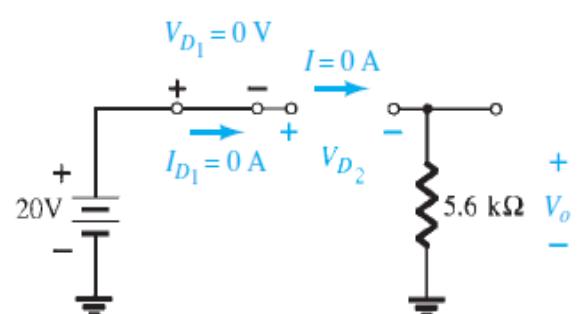
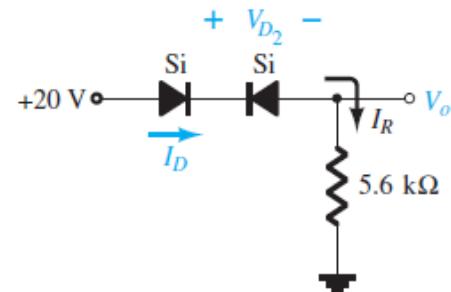
$$V_o = I_R R = I_D R = (0 \text{ A}) R = 0 \text{ V}$$

$$V_{D2} = V_{\text{open circuit}} = E = 20 \text{ V}$$

$$E - V_{D1} - V_{D2} - V_o = 0$$

$$\begin{aligned} V_{D2} &= E - V_{D1} - V_o = 20 \text{ V} - 0 - 0 \\ &= 20 \text{ V} \end{aligned}$$

$$V_o = 0 \text{ V}$$



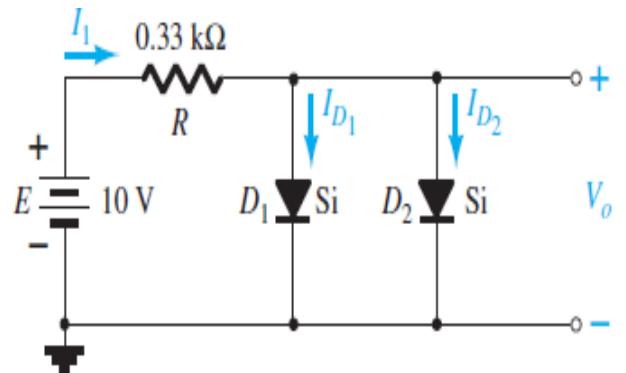
PARALLEL AND SERIES-PARALLEL CONFIGURATIONS

EXAMPLE 5:

Determine V_o , I_1 , ID_1 , and ID_2 for the parallel diode configuration

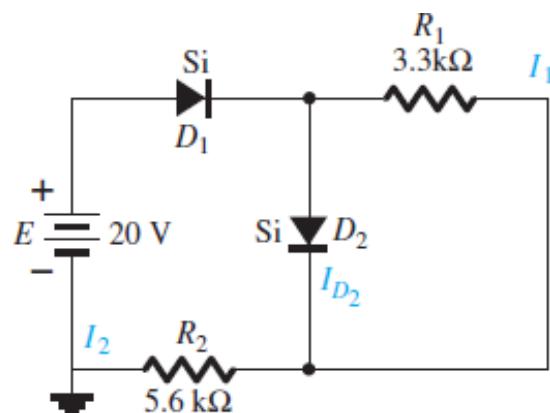
$$I_1 = \frac{V_R}{R} = \frac{E - V_D}{R} = \frac{10\text{ V} - 0.7\text{ V}}{0.33\text{ k}\Omega} = 28.18\text{ mA}$$

$$ID_1 = ID_2 = \frac{I_1}{2} = \frac{28.18\text{ mA}}{2} = 14.09\text{ mA}$$



H.W:

Determine the currents I_1 , I_2 , and ID_2 for the network

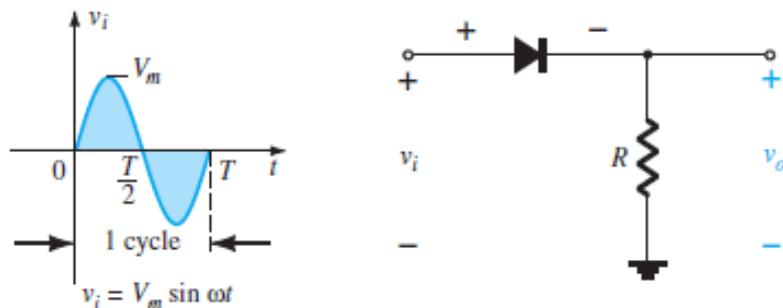


Sinusoidal Inputs

1.HALF-WAVE RECTIFICATION

The diode analysis will now be expanded to include time-varying functions such as the sinusoidal waveform and the square wave. There is no question that the degree of difficulty will increase, but once a few fundamental maneuvers are understood, the analysis will be fairly direct and follow a common thread.

The simplest of networks to examine with a time-varying signal appears in figure. For the moment we will use the ideal model (note the absence of the Si, Ge, or GaAs label) to ensure that the approach is not clouded by additional mathematical complexity.



Over one full cycle, defined by the period T of figure, the average value (the algebraic sum of the areas above and below the axis) is zero. The circuit of above figure, called a **half-wave rectifier**, will generate a waveform v_o that will have an average value of particular use in the ac- to-dc conversion process. When employed in the rectification process, a diode is typically referred to as a **rectifier**.

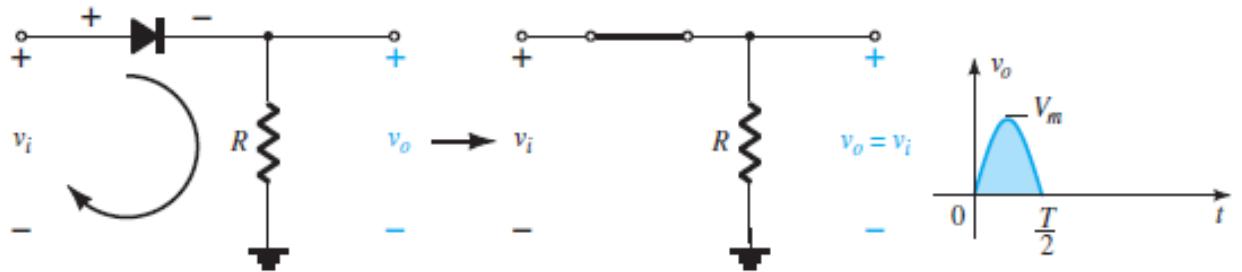
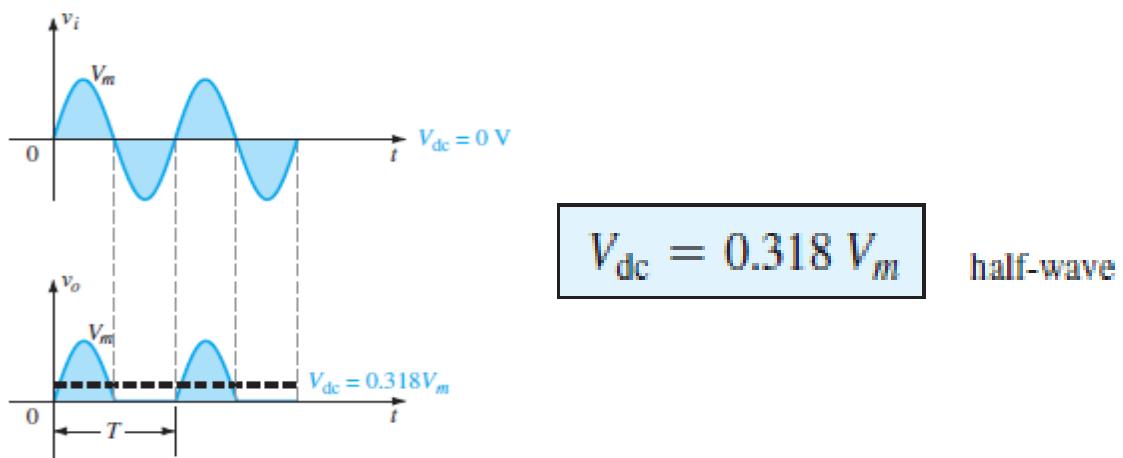
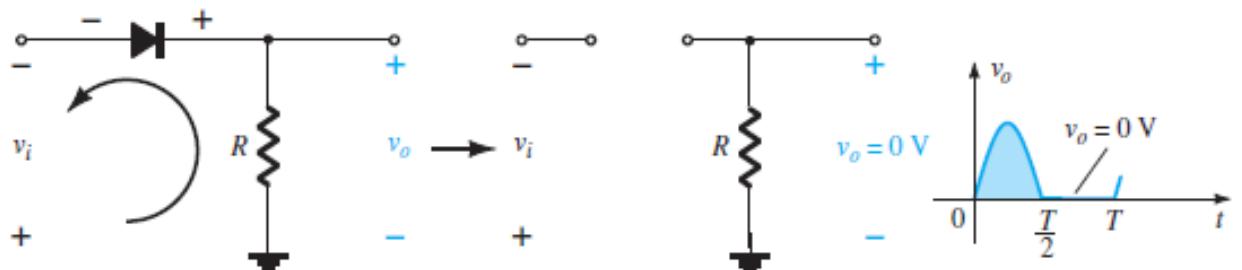
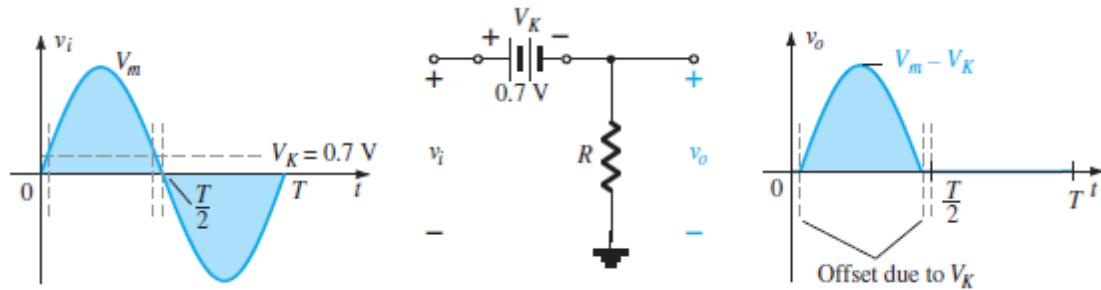


FIG. 2.45
Conduction region ($0 \rightarrow T/2$).



if V_m is sufficiently greater than V_K

The effect of using a silicon diode with $V_K = 0.7 \text{ V}$ is demonstrated in Fig. below for the forward-bias region. The applied signal must now be at least 0.7 V before the diode can turn “on.” For levels of v_i less than 0.7 V , the diode is still in an open-circuit state and $v_o=0 \text{ V}$, as shown in the same figure. When conducting, the difference between v_o and v_i is a fixed



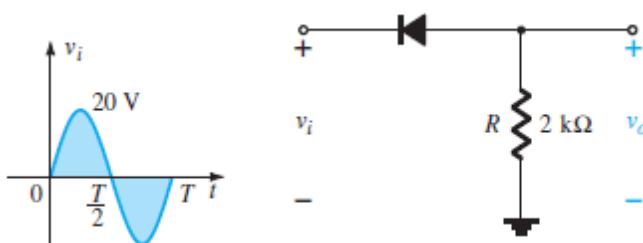
level of $V_K=0.7 \text{ V}$ and $V_o = V_i - V_K$, as shown in the figure. The net effect is a reduction in area above the axis, which reduces the resulting dc voltage level. For situations where $V_m \gg V_K$, the following equation can be applied to determine the average value with a relatively high level of accuracy.

$$V_{dc} \approx 0.318(V_m - V_K)$$

In fact, if V_m is sufficiently greater than V_K , is often applied as a first approximation for V_{dc} .

EXAMPLE 6

- Sketch the output v_o and determine the dc level of the output for the network of the figure.
- Repeat part (a) if the ideal diode is replaced by a silicon diode.

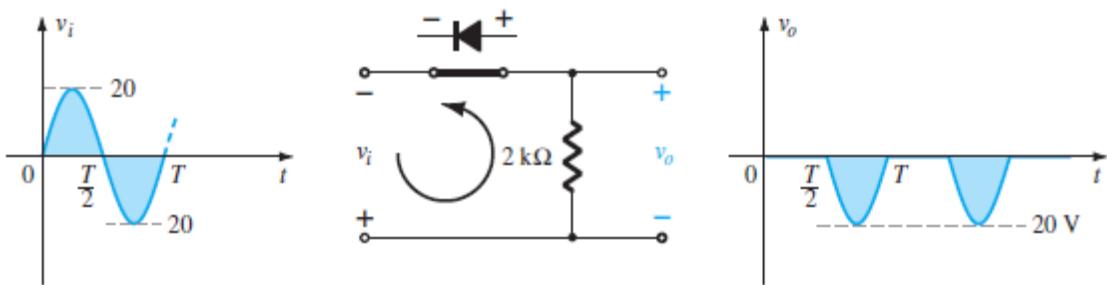


Solution:

- In this situation the diode will conduct during the negative part of the input as shown in figure below, and v_o will appear as shown in the same figure. For the full period, the dc level is

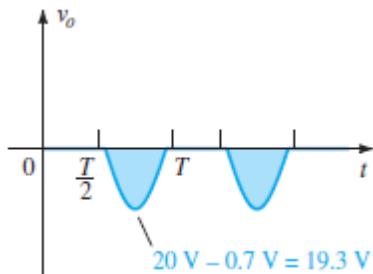
$$V_{dc} = -0.318V_m = -0.318(20\text{ V}) = -6.36\text{ V}$$

The negative sign indicates that the polarity of the output is opposite to the defined polarity.



b. For a silicon diode, the output has the appearance of the figure below.

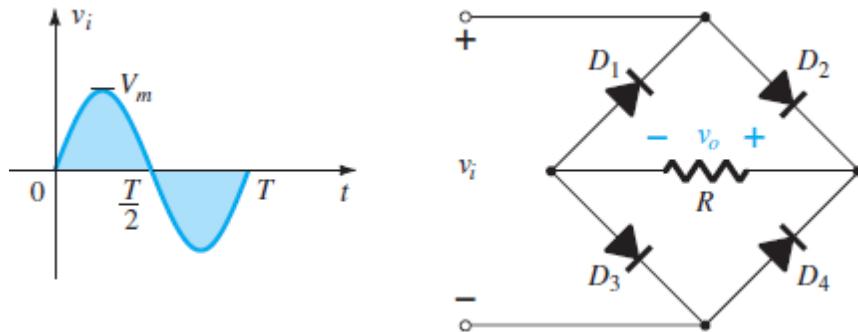
$$V_{dc} \approx -0.318(V_m - 0.7\text{ V}) = -0.318(19.3\text{ V}) \approx -6.14\text{ V}$$



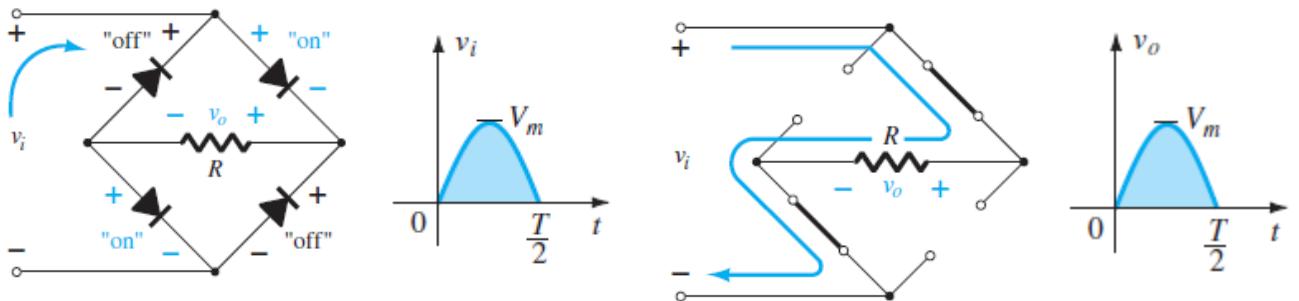
2. FULL -WAVE RECTIFICATION

A-Bridge Network:

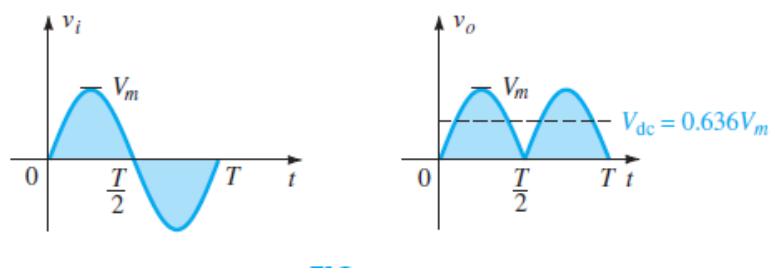
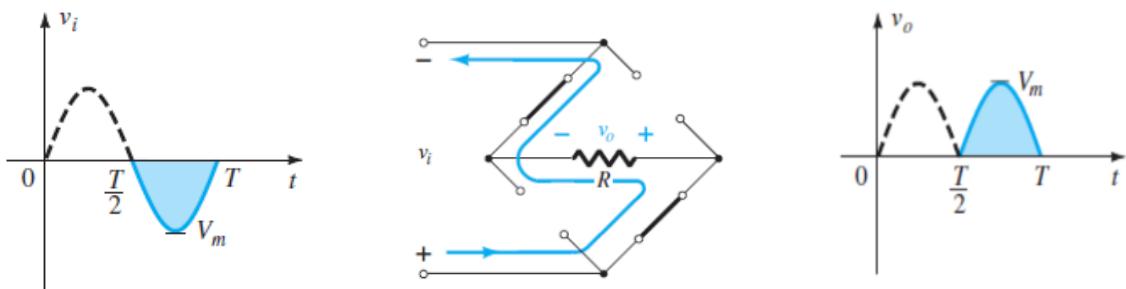
The dc level obtained from a sinusoidal input can be improved 100% using a process called *full-wave rectification*



The resulting polarities across the ideal diodes are also shown in figure to reveal that $D2$ and $D3$ are conducting, whereas $D1$ and $D4$ are in the “off” state.



For the negative region of the input the conducting diodes are $D1$ and $D4$, resulting in the configuration of figure below.



Since the area above the axis for one full cycle is now twice that obtained for a half-wave system, the dc level has also been doubled and

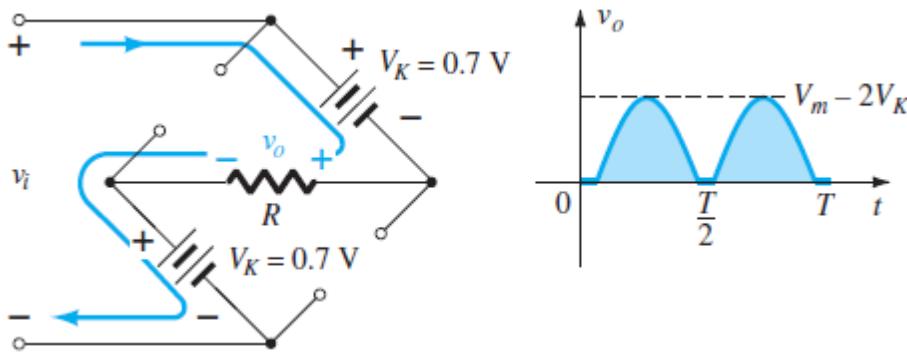
$$V_{dc} = 2(0.318V_m)$$

$$V_{dc} = 0.636 V_m \quad \text{full-wave}$$

If silicon rather than ideal diodes is employed as shown in figure below, the application of Kirchhoff's voltage law around the conduction path results in

$$v_i - V_K - v_o - V_K = 0$$

$$v_o = v_i - 2V_K$$



The peak value of the output voltage v_o is therefore

$$V_{o_{max}} = V_m - 2V_K$$

For situations where $V_m \gg 2V_K$, the following equation can be applied for the average value with a relatively high level of accuracy:

$$V_{dc} \cong 0.636(V_m - 2V_K)$$

Then again, if V_m is sufficiently greater than $2V_K$, then Equation $V_{dc} = 0.636 V_m$ is often applied as a first approximation for V_{dc} .